

Seismic Modeling, Migration and Velocity Inversion Tomography

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Outline

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Tomography

- Residual Tomography

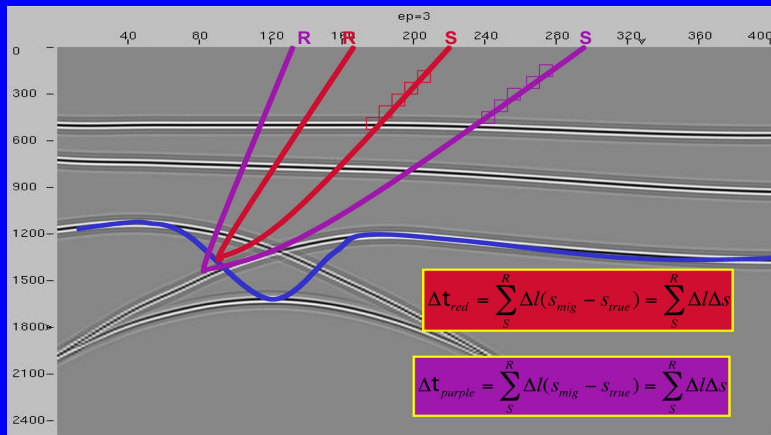
Outline

- 1 **Tomography**
 - Residual Tomography

Tomography after Migration

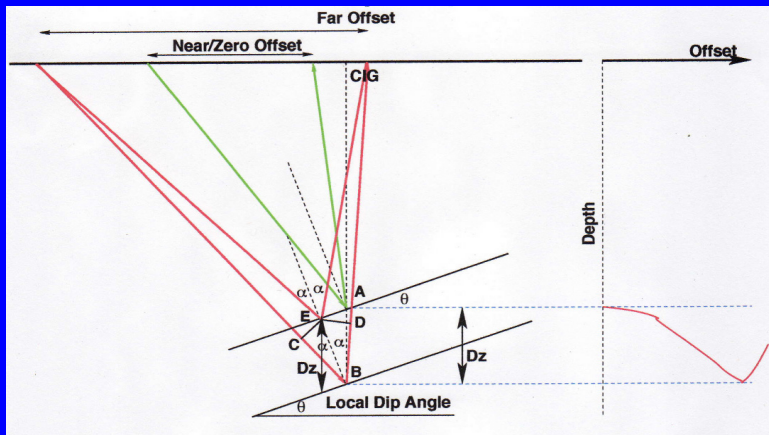
- Residual tomography
 - Generally applied after iterative shot-spread analysis has run its course
 - Based on
 - Local "best" image dip
 - Offset differences from gathers

Residual Tomography



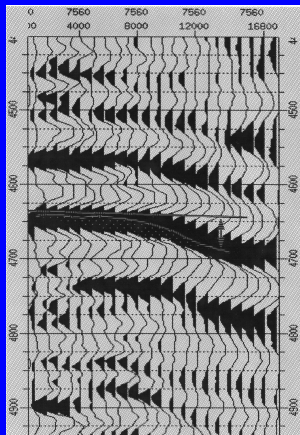
Tomographic geometry.

Residual Tomography



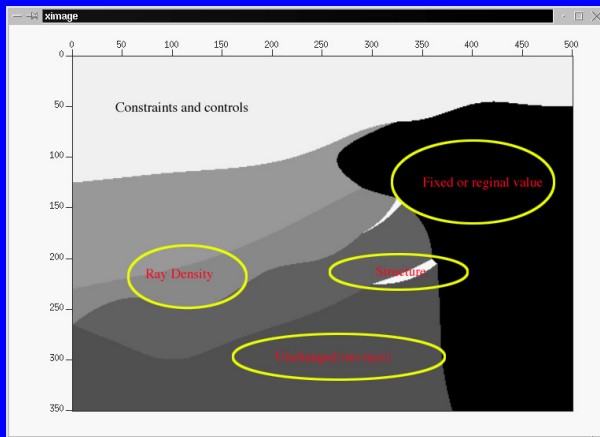
Tomographic geometry.

Tomographic Input Requirements



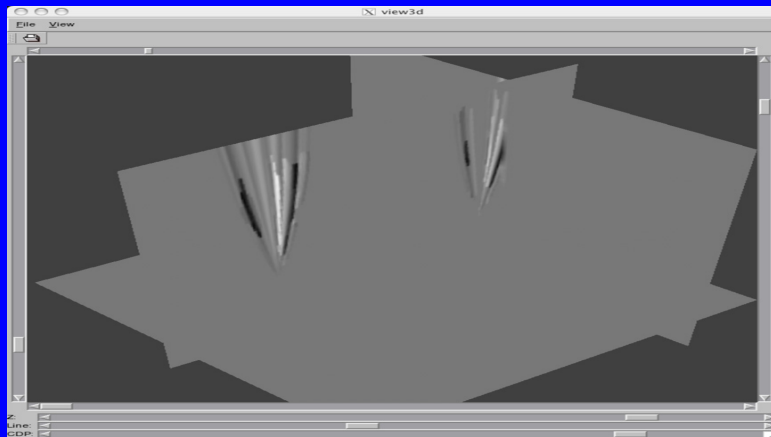
Residual depths as input to tomography.

Constraining Tomography



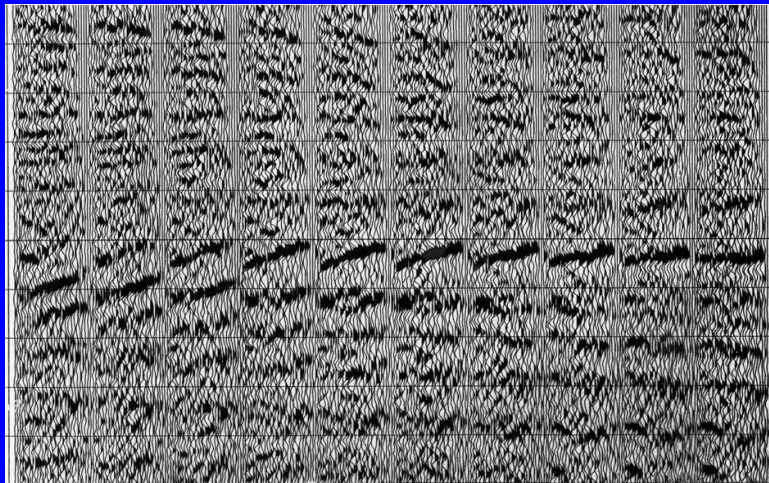
Natural Tomographic Constraints

Residual Tomography



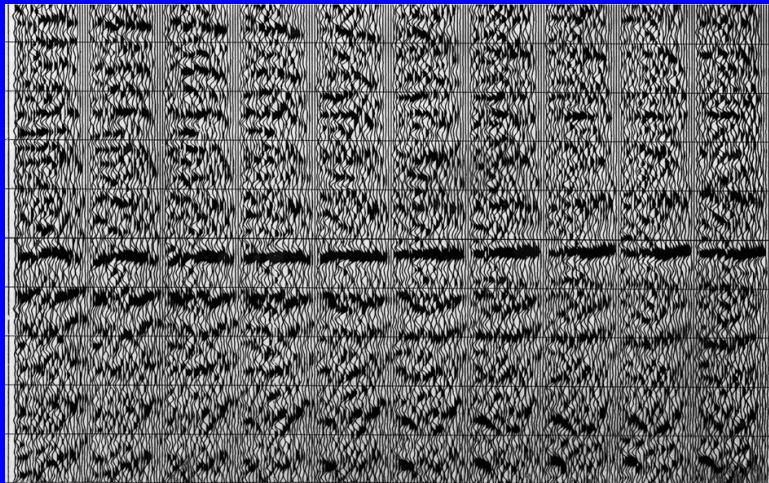
Tomographic back projection.

Non-Flat Gathers Before



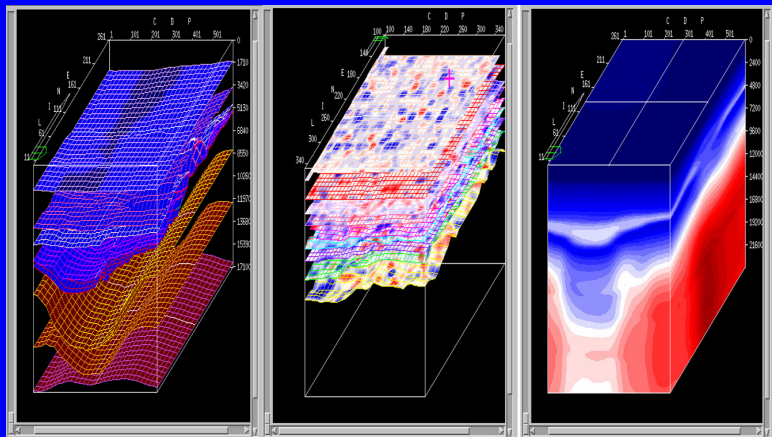
Non flat gathers.

Flat Gathers After



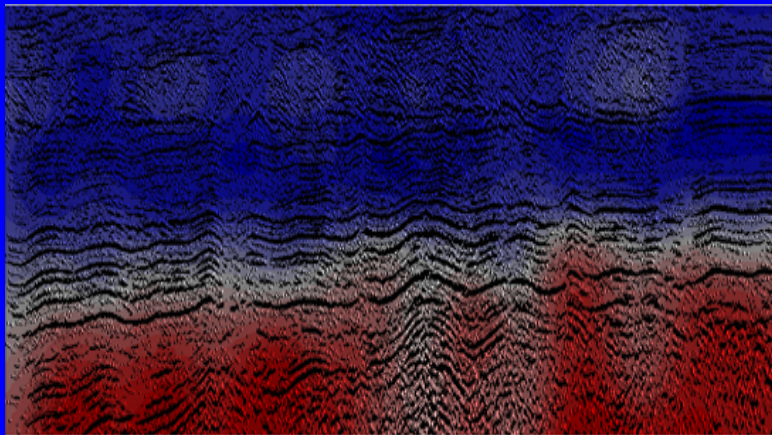
Flat gathers.

Tomographic Updating



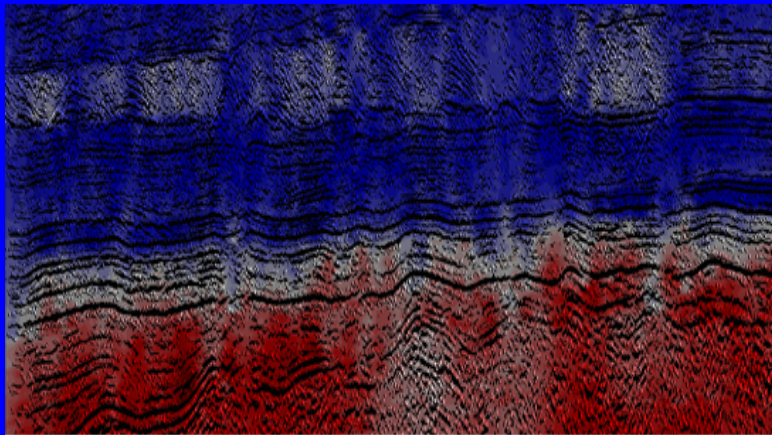
Horizon Based Tomography

Tomographic Example from Alaska



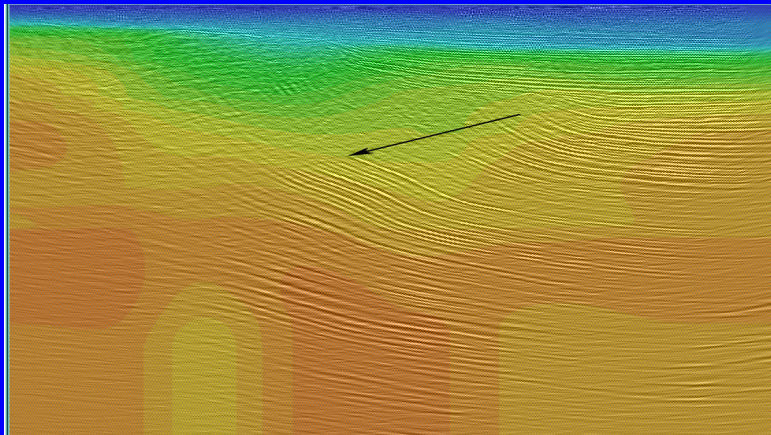
Alaska land data image without tomography

Tomographic Example from Alaska



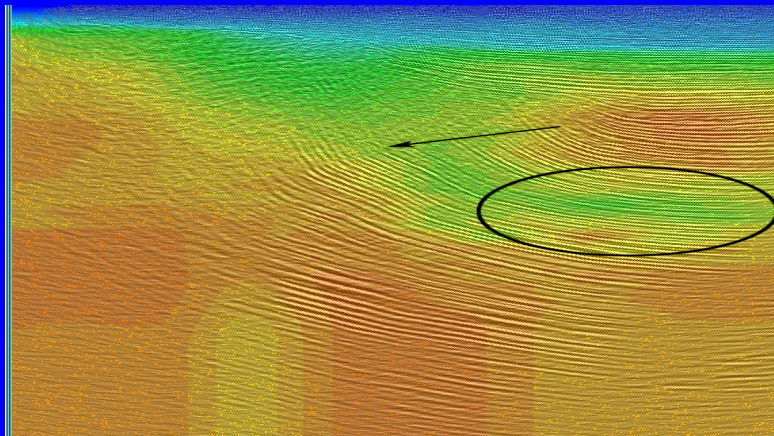
Alaska land data image with tomography

Tomographic Example from Wyoming



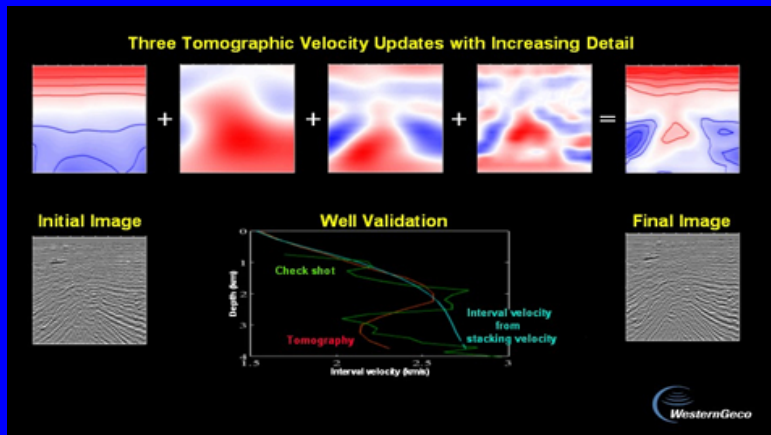
Wyoming land data image without tomography

Tomographic Example from Wyoming



Wyoming land data image with tomography

Tomographic Example from the Gulf of Mexico



Gulf of Mexico tomographic example. After Marta Jo Woodward. Courtesy WesternGeco

Tomographic Input Requirements

- Required input to residual tomography
 - A good migration velocity field
 - A current set of horizons or
 - Local dip everywhere
 - As many horizons as possible.
 - Picked set of residual depths for each common offset or angle gather

Questions?